

Exercise 1. For technical reasons, it is easier to write the conformal map as

$$f(z) = \frac{\alpha z + \beta}{\bar{\beta}z + \bar{\alpha}}$$

where $\alpha, \beta \in \mathbb{C}$ and $|\alpha| > |\beta|$ (by dividing the numerator and denominator by $|\alpha|$, we return to the usual form). Now, the equation $f(e^{i\theta}) = e^{i\varphi}$ is equivalent to

$$e^{i\theta}\alpha + \beta = e^{i(\theta+\varphi)}\bar{\alpha} + e^{i\varphi}\bar{\beta},$$

which yields, after identifying the real and imaginary parts, to

$$\begin{cases} (\cos(\theta) - \cos(\varphi))\operatorname{Re}(\alpha) - (\sin(\theta) + \sin(\varphi))\operatorname{Im}(\alpha) + (1 - \cos(\theta + \varphi))\operatorname{Re}(\beta) - \sin(\theta + \varphi)\operatorname{Im}(\beta) = 0 \\ (\sin(\theta) - \sin(\varphi))\operatorname{Re}(\alpha) + (\cos(\theta) + \cos(\varphi))\operatorname{Im}(\alpha) - \sin(\theta + \varphi)\operatorname{Re}(\beta) + (1 + \cos(\theta + \varphi))\operatorname{Im}(\beta) = 0. \end{cases}$$

We rewrite it in a matrix form as

$$\begin{pmatrix} \cos(\theta) - \cos(\varphi) & -(\sin(\theta) + \sin(\varphi)) \\ \sin(\theta) - \sin(\varphi) & \cos(\theta) + \cos(\varphi) \end{pmatrix} \begin{pmatrix} \operatorname{Re}(\alpha) \\ \operatorname{Im}(\alpha) \end{pmatrix} + \begin{pmatrix} 1 - \cos(\theta + \varphi) & -\sin(\theta + \varphi) \\ -\sin(\theta + \varphi) & 1 + \cos(\theta + \varphi) \end{pmatrix} \begin{pmatrix} \operatorname{Re}(\beta) \\ \operatorname{Im}(\beta) \end{pmatrix} = 0.$$

Notice that both matrices are singular. Using the following sum-to-product formulae

$$\begin{cases} \sin(\theta) \pm \sin(\varphi) = 2 \sin\left(\frac{\theta \mp \varphi}{2}\right) \cos\left(\frac{\theta \mp \varphi}{2}\right) \\ \cos(\theta) + \cos(\varphi) = 2 \cos\left(\frac{\theta + \varphi}{2}\right) \cos\left(\frac{\theta - \varphi}{2}\right) \\ \cos(\theta) - \cos(\varphi) = -2 \sin\left(\frac{\theta + \varphi}{2}\right) \sin\left(\frac{\theta - \varphi}{2}\right) \end{cases}$$

and the identities

$$\begin{cases} \cos(2x) = 2 \cos^2(x) - 1 = 1 - \sin^2(x) \\ \sin(2x) = 2 \cos(x) \sin(x) \end{cases}$$

the system becomes

$$\begin{pmatrix} -2 \sin\left(\frac{\theta + \varphi}{2}\right) \sin\left(\frac{\theta - \varphi}{2}\right) & -2 \sin\left(\frac{\theta + \varphi}{2}\right) \cos\left(\frac{\theta - \varphi}{2}\right) \\ 2 \sin\left(\frac{\theta - \varphi}{2}\right) \cos\left(\frac{\theta + \varphi}{2}\right) & 2 \cos\left(\frac{\theta + \varphi}{2}\right) \cos\left(\frac{\theta - \varphi}{2}\right) \end{pmatrix} \begin{pmatrix} \operatorname{Re}(\alpha) \\ \operatorname{Im}(\alpha) \end{pmatrix} + \begin{pmatrix} 2 \sin^2\left(\frac{\theta + \varphi}{2}\right) & -2 \cos\left(\frac{\theta + \varphi}{2}\right) \sin\left(\frac{\theta + \varphi}{2}\right) \\ -2 \cos\left(\frac{\theta + \varphi}{2}\right) \sin\left(\frac{\theta + \varphi}{2}\right) & 2 \cos^2\left(\frac{\theta + \varphi}{2}\right) \end{pmatrix} \begin{pmatrix} \operatorname{Re}(\beta) \\ \operatorname{Im}(\beta) \end{pmatrix} = 0.$$

Notice that first line has a $\sin\left(\frac{\theta + \varphi}{2}\right)$ in factor and that the second line has a $\cos\left(\frac{\theta + \varphi}{2}\right)$, and that those two numbers cannot be simultaneous 0. Simplifying the first equation by $2 \sin\left(\frac{\theta + \varphi}{2}\right)$ yields the equation

$$-\sin\left(\frac{\theta - \varphi}{2}\right) \operatorname{Re}(\alpha) - \cos\left(\frac{\theta - \varphi}{2}\right) \operatorname{Im}(\alpha) + \sin\left(\frac{\theta + \varphi}{2}\right) \operatorname{Re}(\beta) - \cos\left(\frac{\theta + \varphi}{2}\right) \operatorname{Im}(\beta) = 0,$$

and simplifying the second one by $\cos\left(\frac{\theta+\varphi}{2}\right)$ yields

$$\sin\left(\frac{\theta-\varphi}{2}\right)\operatorname{Re}(\alpha) + \cos\left(\frac{\theta-\varphi}{2}\right)\operatorname{Im}(\alpha) - \sin\left(\frac{\theta+\varphi}{2}\right)\operatorname{Re}(\beta) + \cos\left(\frac{\theta+\varphi}{2}\right)\operatorname{Im}(\beta) = 0, \quad (1)$$

Those two equations are the same, so the system reduces to the equation (1). Now, if $0 \leq \theta_1 < \theta_2 < \theta_3 < 2\pi$ and $0 \leq \varphi_1 < \varphi_2 < \varphi_3 < 2\pi$, it is easy to show that the matrix

$$\begin{pmatrix} \sin\left(\frac{\theta_1-\varphi_1}{2}\right) & \cos\left(\frac{\theta_1-\varphi_1}{2}\right) & -\sin\left(\frac{\theta_1+\varphi_1}{2}\right) & \cos\left(\frac{\theta_1+\varphi_1}{2}\right) \\ \sin\left(\frac{\theta_2-\varphi_2}{2}\right) & \cos\left(\frac{\theta_2-\varphi_2}{2}\right) & -\sin\left(\frac{\theta_2+\varphi_2}{2}\right) & \cos\left(\frac{\theta_2+\varphi_2}{2}\right) \\ \sin\left(\frac{\theta_3-\varphi_3}{2}\right) & \cos\left(\frac{\theta_3-\varphi_3}{2}\right) & -\sin\left(\frac{\theta_3+\varphi_3}{2}\right) & \cos\left(\frac{\theta_3+\varphi_3}{2}\right) \end{pmatrix}$$

has rank 3, which yields a solution α, β (to be precise, a one-dimensional family of solutions), and renormalising it by $|\alpha|$, it becomes unique as an element of $[0, 2\pi] \times \mathbb{D}$ (written $(e^{i\psi}, a)$ with $0 \leq \psi < 2\pi$).

Exercise 2. 1. One inequality is trivial since for all $\varphi \in C_c^\infty(\mathbb{D}, \mathbb{R}^3)$ such that $\|\varphi\|_{L^\infty(\mathbb{D})} \leq 1$, we have

$$\int_{\mathbb{D}} \langle \partial_x u \times \partial_y u, \varphi \rangle dx dy \leq \left(\int_{\mathbb{D}} |\partial_x u \times \partial_y u| dy dy \right) \|\varphi\|_{L^\infty(\mathbb{D})} \leq \int_{\mathbb{D}} |\partial_x u \times \partial_y u| dy dy.$$

On the other hand, for all $0 < \varepsilon < 1$, regularising by convolution the bounded, compactly supported function

$$\frac{\partial_x \varphi \times \partial_y \varphi}{|\partial_x \varphi \times \partial_y \varphi|} \mathbf{1}_{\mathbb{D}(0, 1-\varepsilon)}$$

by convolution, we find a sequence $\{\varphi_n\}_{n \in \mathbb{N}} \in \mathcal{D}(\mathbb{D}, \mathbb{R}^3)$ such that $\|\varphi_n\|_{L^\infty(\mathbb{D})} \leq 1$ and such that for all $f \in L^1(\mathbb{D}, \mathbb{R}^3)$, we have

$$\int_{\mathbb{D}} \langle f, \varphi_n \rangle dx dy \xrightarrow{n \rightarrow \infty} \int_{\mathbb{D}(0, 1-\varepsilon)} \left\langle f, \frac{\partial_x \varphi \times \partial_y \varphi}{|\partial_x \varphi \times \partial_y \varphi|} \right\rangle dx dy.$$

Applying this to $f = \partial_x u \wedge \partial_y u$ and letting $\varepsilon \rightarrow 0$, the result follows.

2. Integrating by parts, we get

$$\int_{\mathbb{D}} \langle \partial_x u_n \times \partial_y u_n, \varphi \rangle dx dy = -\frac{1}{2} \int_{\mathbb{D}} (\langle u_n \times \partial_y u_n, \partial_x \varphi \rangle + \langle \partial_x u_n \times u_n, \partial_y \varphi \rangle) dx dy.$$

Thanks to Rellich-Kondrachov theorem, $\{u_n\}_{n \in \mathbb{N}}$ converges strongly in L^2 and since φ is smooth, a result of the course shows that

$$\int_{\mathbb{D}} (\langle u_n \times \partial_y u_n, \partial_x \varphi \rangle + \langle \partial_x u_n \times u_n, \partial_y \varphi \rangle) dx dy \xrightarrow{n \rightarrow \infty} \int_{\mathbb{D}} (\langle u \times \partial_y u, \partial_x \varphi \rangle + \langle \partial_x u \times u, \partial_y \varphi \rangle) dx dy.$$

3. We have

$$\begin{aligned} \int_{\mathbb{D}} \langle \partial_x u \times \partial_y u, \varphi \rangle dx dy &= \lim_{n \rightarrow \infty} \int_{\mathbb{D}} \langle \partial_x u_n \times \partial_y u_n, \varphi \rangle dx dy \\ &\leq \liminf_{n \rightarrow \infty} \sup \left\{ \int_{\mathbb{D}} \langle \partial_x u_n \times \partial_x u_n, \psi \rangle dx dy : \psi \in C_c^\infty(\mathbb{D}, \mathbb{R}^3), \|\psi\|_{L^\infty(\mathbb{D})} \leq 1 \right\} \\ &= \liminf_{n \rightarrow \infty} A(u_n). \end{aligned}$$

Exercise 3. We know by a previous exercise (Série 6, Exercise 3) that the homogenous H^s norm squared is equivalent to

$$\int_0^{2\pi} \int_0^{2\pi} \frac{|u(x) - u(y)|^2}{|x - y|^{1+2s}} dx dy,$$

since since $\sin(x) = x + O(x^3)$, the equivalence follows easily by taking $s = 1/2$.